NAVAL CIVIL ENGINEERING LABORATORY
Port Hueneme, California

Sponsored by NAVAL FACILITIES ENGINEERING COMMAND

DYNAMIC TESTING OF LOAD HANDLING WIRE ROPE AND SYNTHETIC ROPE (U)

January 1970

An Investigation Conducted by

Preformed Line Products Company 5318 St. Clair Avenue Cleveland, Ohio 44103 Project No. M7009-T

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TEST REPORT

DYNAMIC TESTING OF LOAD HANDLING WIRE ROPE AND SYNTHETIC ROPE (U) NAVAL CIVIL ENGINEERING LABORATORY N62397-69-C-0013 PROJECT NO. M9009-T

ABSTRACT

A testing program was initiated by U. S. Naval Civil Engineering Laboratory to conduct dynamic tests on torque balanced wire and synthetic rope. The tests were conducted at the laboratories of Preformed Line Products Company, Cieveland, Chio.

The scope of the work was to provide dato so that a basis can be established to select the best type of line for load-handling purposes in the deep ocean environment. The tests consisted of tension vs elongation, rotation and kink formation, and longitudinal dynamic response.

The tension elongation tests yielded data typical to stranded line construction.

The rotation-kink tests revealed that negligible rotations resulted in the test cables when under load and that no kinks were formed when the load was suddenly released.

The dynamic response tests showed that the measured dynamic stresses were dependent upon the exciting frequency. The natural frequency for the synthetic rope sample was 0.3 cps and 0.6 cps for the wire rope.

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The tests indicated that the highest values of combined static and dynamic stresses occur at resonance which could cause failure of the cable at points of high stress concentration.

It is recommended that some hydraulic parameters and random excitation be introduced in the future testing of this type. Stress relieving fittings should be investigated for use on load handling lines in the ocean environment.

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TEST REPORT

DYNAMIC TESTING OF LOAD HANDLING WIRE ROPE AND SYNTHETIC ROPE (U) NAVAL CIVIL ENGINEERING LABORATORY N62399-69-C-9013 FROJECT NO. M9009-T

Introduction

The testing program described herein was conducted for the Naval Civil Engineering Laboratory, Contract No. N62399-69-C-0013, on government furnished steel wire rape and synthetic rope. The tests were conducted at the laboratories of Preformed Line Products Company, Cleveland, Ohio.

The objective of this work was to provide test data to be analyzed and evaluated as a basis for the selection of the best type of rape for load-handling purposes in the deep ocean environment. The types of tests conducted consisted of tension vs elongation, rotation and kink formation, and longitudinal dynamic response.

TENSION VS ELONGATION TEST

Description of Test Equipment

The equipment used to conduct the tension elongation tests was a horizontal testing machine with a loading aspecity of 50,000 pounds and a spon length of 66 feet. Fig. 1 is a schematic of the equipment.

The test machine has nonrotating clavis ends, one attached to a hydraulic rans and the other to an adjustable dead-and. The hydraulic system has a constant pressure pump with a flow control to vary the loading range. The load synsing system is composed of commercial load cells installed in series with electronic components and a 24-inch dial readout with varying load ranges up to 50,000 pounds.

Because of the substantial differences in the physical properties of the wire rope and the symmetric rope, the test setup was modified to suit the respective test samples. Since the strength of the wire rope exceeded the test machine loading capacity, a force-doubling pulley arrangement was applied between the machine ram and its frome and one end of the test sample. A 200,000-pound load cell was installed in series with the test sample to sense the load and a Paldwin SR-4 Strain Analyzer was employed to measure the tensile load in the test sample as shown in Fig. 2. Optical cathometers were used to measure the elongation. Fig. 3 shows the setup used.

The double palley arrangement was not used for testing the synthetic rope, however, because of the stretch characteristics of the rope. The calculated elongation of the rope revealed that the machine rom travel was insufficient. Therefore, turn-buckles were used in line with the test sample to take up the initial stretch. Fig. 4 shows the test setup used. Elongation was measured with a steel tape to the nearest 1/8 inch.

Test Somples

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All tests were performed using government furnished steel wire rope and synthetic rope. The wire rope was new. However, there was evidence that the synthetic rope had been in service prior to testing. The contractor was responsible for test sample terminations. The loops in the synthetic rope samples were formed by Samson Cordage, Boston, Massachusetts and the wire rope was terminated with spelter socket fittings. Specifications of the respective ropes are listed in Figs. 5 and 6.

Test Proceedure

Each test sample was placed in the test machine and pulled taut to an initial tension of 1,000 pounds. A 60-inch gage length was then marked with an accuracy of $\pm 1/16$ inch.

Additional tensile load was then applied at the rate of 0.619 inches per minute in 5,000-pound increments. These incremental loads were held for one minute. During the load-holding periods, the corresponding elongations of the gage length were measured at the beginning and again at the end of the holding periods. The duplicate measurements were made in anticipation of possible human errors and for possible creep in the line material. Measurements were taken up to 60 per cent of the rated breaking strength of the majorial. The test samples were then pulled to destruction noting the approximate breaking load.

Test Results

Test results for the wire tope are tabulated in Tables I and II and shown in curve form in Fig. 7.

Test results for the synthetic rope are tabulated in Table III and shown in curve form in Fig. 8.

The ultimate fracture occurred at or near the terminaling device for both types of material. Fig. 9 reveals that the wire rope failed at the edge of the zinc sacket and Fig. 10 clearly shows the failure of the synthetic rope at the junction of the loop and the long end of the rope.

Discussion

The following problems were encountered during this series of tests.

The breaking strength of the wire rope exceeded the test machine capa ity.

A method to obtain higher loading was devised to utilize the existing test equipment.

The ram travel of the test machine was limited. A system and technique to take up the extensive stretch of synthetic rope had to be devised and employed.

Failures of the test samples below the rated breaking strength was a serious problem. In the case of the synthetic rope, the required elongation reading prior to failure was not measured because of the premature failure. This also caused concern for the safety of the laboratory personnel who were taking elongation readings. Nonrepeatability and deviation in measured data was evident.

In order to obtain confident elongation readings on the wire rope, several samples were tested. In the first samples, problems developed with the hydraulic system and the sample was cycled several times before it failed. The test sample was loaded to the capacity of the test machine and then the load was released and a pulley arrangement was installed. This technique resulted in a discontinuity and a hysteresis curve as shown in Fig. 11.

A second sample was tested. There was a strong deviation of data in this test and upon inspection of the test sample it was noted that at one socket fitting a strand had slipped our prematurely which could have caused the erratic readings. This data was discarded.

The most dependable data was obtained from the third sample tested and the data is presented in Fig. 7.

Additional samples of the synthetic rope were not tested because it was decided that the one test clearly indicated the weakness of the synthetic rope termination. To conduct further testing would have required additional time and expenditure to design, develop and manufacture a special end litting to hold the full-rared strength of the synthetic rope.

For multistranded cable such as used in these tests, the attainment of full rated breaking strength depends a great deal upon the uniform loading of the individual strands. This is not a simple task when using most commercial fittings.

Due to intrinsic variations in the tensile and physical properties of a terminated cable, several test samples should be tested in order to yield enough data to determine an effective holding strength and a representative cable modulus of elasticity. Unfortunately, extra test samples were not available because of the limited amount of material on hand and for the economic reasons mentioned earlier.

ROTATION AND KINK FORMATION TESTS

Test Equipment and Setup

The laboratory was faced with the problem of testing relatively long lengths at various high loads in a vertical configuration. Existing laboratory equipment did not have the required amount of weight, the lifting capacity nor the needed heights. Therefore, it was decided to conduct the rotation and kink tests outdoors at a local scrap yard where the weights and a crane with lifting and height capacity were available.

Each test sample was vertically suspended from a boom having a locked clevis attachment at the top. The bottom end of the suspended test sample was loaded with attached weights and was free to rotate.

Four groups of preweighed weights were used for each test sample. Weights of 2,250, 4,500, 6,900, 9,000 pounds were used to test the synthetic rope samples, and 4,100, 7,800, 11,800, 15,400 pounds were used to test the wire rope samples.

A 36-inch machinist scale was suspended from an upper gage mark of each test sample to measure elongation.

Visual observations of the associated rotations were made by means of stationary and rotating markers, one on the ground and one on the attached weight assembly, respectively.

Test Samples

Eight test samples were prepared as follows:

Test Sample No. i	17 feet	2 inches	Synthetic
Test Sample No. 2	10 feet	11 5/8 inches	Wire
Test Sample No. 3	19 feet	5/8 inch	Synthetic
Test Sample No. 4	10 feet	11 1/8 inches	Wire
Test Sample No. 5	78 feet	9 5/8 inches	Synthetic
Test Sample No. 6	10 fact	i i 5/8 inches	Wire
Test Sample No. 7	17 feet	11 1/3 inches	Synthetic
Test Somple No. 8	11 feet	i inch	Wire

The lengths for the wire rope were measured from mouth-to-mouth of the specket fitting. The lengths for the synthetic rope were measured from pin-to-pin.

Tes? Procedure

At the beginning of each test, the test samples were preloaded with a tare load of 200 pounds. At this time the initial naminal length was measured, the 120-inch gage length was marked, visual alignment of the end fittings was ascertained and a bench mark, or zero reading, for subsequent rotation was obtained.

This sopple was thus fawered and the required weights were attached to the test sample. Each loaded test sample was then raised off the ground. During the raising process, the weighted end was manually held by a technician in the zero position. The manual rotational restraint was then released and the assembly was allowed to rotate and oscillate freely. Observations of the direction and magnitude of the maximum rotations were made and recorded. When the oscillations stopped, the elangation position of the lower gage mark was measured and recorded. (Fig. 12)

The weighted essembly was then dropped to the ground by rapidly lowering the boom. The test sample was allowed to collapse several feet. Observations for kink formation were then made. Figs. 13 and 14 show the collapsed cable with no kinks.

Test Results

The results are tabulated in Tables IV and V. Graphs were not constructed because the observed angular rotations were comparatively small and inconsistent. An example of this inconsistency can be seen in Table V. During the autdoor testing of the synthetic rope, the sample rotated 225 degrees at a load of 4,500 pounds. At a load of 6,900 pounds, the sample rotated 45 degrees, and at 9,000 pounds, 135 degrees.

Discussion

Prior to testing, it was assumed that the constructionally tarque-balanced test samples would tend to twist when loaded axially and that they would form characteristic kinks upon sudden release of the tensile load. The test results indicate otherwise, and all the tests showed comparatively little or no rotation and no kinks were formed. Because of the unexpected results, several repetitious tests were run. Also, a suries of rechecks in the laboratory on the horizontal testing machine were conducted to compare with data obtained autdoors. In the laboratory the test samples were attached to a rotating clevis of the suff-bearing nonstruction on one end to allow the sample freedom of rotation during loading. Despite some frictional resistance of the rotating clevis, these laboratory rechecks substantially corresponded with the outdoor results regarding the order of magnitude for the expected angular rotation. Again, these angular movements were way small in comparison with what might be expected from multistrand cable not having torque-balance design features.

These test results indicate that the manufacturer's claims to a tarque-balanced line were virtually substantiated, at least for the lengths of the test samples employed. This does not imply that the test samples were free of tarque conditions. The test results brought attention to the need for finite rotational measurements, when this does is required to extrapolate sample lengths to substantially longer lengths of tarque-balanced cable.

The results of no kink formation indicated that the tarque developed under land was negligible for these cable constructions, resulting in no rotation. Therefore, there was no cable distortion which would cause kinks in the cable, should a slack condition suddenly develop.

DYNAMIC RESPONSE

Considerations Prior to Testing

The laboratory was faced with numerous test-engineering problems prior to testing. These problems and their respective solutions are described as follows.

Interpretation of realistic sec-state periods corresponded to relatively low frequencies in tensile excitation which were coupled with relatively small cyclic specimen displacements.

In order to determine the modifications required to match our existing equipment capabilities with the test performance requirements as outlined, the basic dynamics of the test program were further analyzed. The N.C.E.L. Technical Report No. 433 (AD 631 267) was reviewed and the mathematical model was converted to a laboratory test model. Such efforts revealed the following:

- Fundamental resonance can occur at relatively low frequencies
 for both rope materials, particularly when design parameters were
 scaled down to those of a laboratory test model. Calculations are
 included at the end of the text.
- 2. The magnitude of the cyclic axial displacements did not enter into the dynamic response of the taut-rope mass system.
- 3. The installation of another weight at the driving end of the test span, for the purpose of maintaining a notional rope tension during the cyclic excitation, did not essentially affect the dynamic response, particularly at resonance.

Practical test equipment modifications, and a test procedure and setup were devised and employed. Such equipment was believed to provide valid simulation of the dynamics involved in a vertical ocean-lift system.

The equipment array, as shown in Figs. 15 and 16, was designed, fabricated and assembled for conducting this series of tests.

After some preliminary tests using the wire rope test sample (aquipment and technique shake-down period), the dynamic forces at resonance indicated the need for substantial rope terminating fittings. This requirement became acute for the synthetic rope material, in light of tise termination deficiency experienced with the loop termination during the previous tension elangation tests.

Because of this necessity, an encapsulated tensination of the synthetic rape was developed and was cycled between 10,000 and 20,000 pounds (expected region under the dynamic test equipment) in the tensile testing machine without any slippage.

Test Samples

Both types of rope material were furnished by N.C.E.L. they were cut to length and equipped with terminating fittings. The length of the wire rope test sample was 116 feet 7 inches. The length of the synthetic rope test sample was 117 feet 3 inches. Both lengths were measured under a nominal tension of 16,600 pounds tension while resting in the test span.

The terminating littings for the wire rape were identical to those described and shown in Fig. 9.

The terminating fittings for the synthetic rope were constructed as follows:

- a. The core and the auter layer strands were untwined and thuroughly wetted with Scotch-Cast No. 9 resin (3-14 product).
- b. The order-layer strands were circumierentially placed and wedged by a metallic cone piece against the inside well of the clevis-type socket fitting.

- c. The core strands were fed through the large center hole of the wedging cone piece. The extended core strands were radially mushroomed outward.
- d. The entire assembly was than potted with Scotch-Cast No. 9 resin, making particularly certain that sufficient resin was present in the necked cavity of the fitting.

Test Equipment, Setup and Instrumentation

The test equipment, setup and instrumentation were common to both test samples of wire and of synthetic rope. The overall arrangement is shown schematically in Fig. 17. The constituents were as follows:

Abutments provided the supporting structure for the spanned test assembly.

- Guides offered horizontal guidance at three different locations along the span to minimize vibration to the test span.
- Turnbuckles provided a means of fine adjustment in tensioning the test samples to the desired naminal 10,000-pound line tension.

 One clevis stud of each turnbuckle was instrumented with strain gages to measure axial tensile load.
- Pillow Blocks provided the longitudinal guidance for the actuating linkages. These pillow blocks were constructed of Thomson linear ball bearings, thus offering minimal sliding friction.
- Loading Beams & Dead Weights provided load multipliers and the maintenance of line tension. The driving beam end transmitted the sinusoidal excitation. The pivoting beams were constructed with antifriction ball bearings.
- Load Cells were used to sense the tension variations at the input and output ends. The safe working load for both load cells was 18,000 pounds.
- Linear Variable Differential Transformers were used to measure the longitudinal displacements.
- Drive Mechanism provided the cyclic longitudinal displacements at variable frequencies and amplitudes. The mechanism consisted of a variable gear motor, sprocket-chain, jack-shaft reduction stage, driving a variable crank-arm, four-slide mechanism.

 The slider was attached to the pivoted beam through a pin-slot.

Instrumentation Secorder was a Honeywe'l No. 1020 multichannel oscillograph. It was complemented with a Heiland oscillator and carrier amplifiers. The recording galvos were of 1,600 cps response.

Test Procedure

The test samples were installed between the abutments of one of the 125-foot vibration beds. In order to arrive at the correct final installed test sample lengths between the end abutments required a predetermination of the load-free length of the test sample.

For the wire rope, theoretical calculations of the required length were rather straightforward. However, for the synthetic rope, predetermination of the length was not so easily accomplished. The theoretical calculations of the stretch only provided a regional length. The exact length dimension was difficult to determine because of the various inaccuracies of the physical data used to calculate the stretch length when under load. One of these factors was looseness of the external layer of the synthetic rope. Therefore, a trial and error method was used. That is, a length of rope was installed and the length under load was noted. The sample was then removed and shortened and then reterminated. The final load-free length resulted in a much shorter length than the calculations indicated. The test samples were pulled into position by using ratchet type line hoists. The test samples were then secured in the test span when the inline load reached 10,000 pounds for the wire rope and 13,000 pounds for the synthetic rope. When the pulling end device was removed, the span line tension dropped to somewhat below the required test load.

The final nominal tensioning to test load was accomplished by adjusting the turn uckles which were installed in series with the test samples. After acquiring the desired test tension, the guides were attached to eliminate transverse vibration of the test samples.

The required instrumentation used to sense the predetermined test parameters was then installed and calibrated. This instrumentation consisted of two LVDT's to measure the displacement at either end and two load cells to measure the force variations at the input and output end. During the running of the test all the force and displacement signals were simultaneously recorded on the oscillograph.

To reach the low natural frequency of the tested taut-rope mass system, the driver mechanism was started at a speed above resonance, then incrementally swept upward about 5 cps and swept downward until the resonant frequency was reached. At resonance, the driven end of the wire rope displayed significantly large amplitudes of displacement.

In the case of the synthetic rope, resonance was not obtainable from the machine drive because its lowest geared downspeed was not low enough to approach the natural frequency of the system. The method used to obtain the natural frequency was to rap the driven beam at the rate of about two or three times a second until an apparent and sustaining resonance resulted.

In each test, simultaneous oscillographic recordings of the four sensors were taken at incremental excited frequencies with two or three different longitudinal displacement amplitudes. After completing the dynamic test, the setups were disassembled and the individual moving parts were weighed. A list of these weights is presented in Table XVII, so that correlations with the associated analytics can be accomplished.

Test Results

Test results for the wire rope are tabulated in Tables VI through X and shown in curve form in Fig. 18.

Test results for the synthetic rope are tabulated in Tables XI through XVI and shown in curve form in Fig. 19.

A typical recording of the dynamic response data is presented in Fig. 20.

These tests clearly indicated that the dynamic amplitudes and stress in the rope were dependent upon the exciting input frequency. This dependence can be more specifically related to the ratio of the exciting frequency and the natural frequency for a given taut-rope mass system. Although maximum dynamic amplitudes were always obtained at resonance, maintaining resonance was observed to be very difficult because the resonance frequencies peaked over sharply and the delineation between resonant and nonresonant states was quite abrupt. Consequently, most of the test results were obtained under nonresonant conditions. At these conditions, the driven end was virtually at a standstill. This indicated that the input-exciting displacements caused elastic elongations in the test samples.

Since the synthetic rope has a lower spring constant and associated dampening, it had to be excited with larger longitudinal displacements than the wire rope in order to yield readable data.

Discussion

Selection of the frequency spectrum

The taut rope-mass arrangement of this experimentation could be compared to a spring-mass system with the support being sinusoidally excited. The natural frequency of such a simplified system is dependent upon the effective spring constant and the suspended mass.

In relating laboratory testing to a specific oceanographic application, the k/m expression can vary widely. Such large variations can be caused by the rope material, its length and the "virtuar" mass of the submerged constituents. The laboratory experiments indicated the rope material and length appeared to be the most effective parameters. Since the effective spring constant, k, varies

inversely with the length of a line, relatively low natural frequencies would be expected. In this regard, the experimental setup simulated a considerably longer rope length than the test sample due to the modifying dynamic effect of the lever arm ratio, a/l, for the pivoting beam.

The employment of relatively low test frequencies can be further supported by laboratory test efforts in attempting to obtain and observe maximum dynamic stresses in the cable. Maximum dynamic stresses are most easily obtained at fundamental resonance; that is when the frequency of the exciting source equals the fundamental frequency of the taut rope system. In reference to sea applications, the heaving movement of a ship is characterized by low frequencies.

Therefore, when the above aspects are combined, the selection of the reported test frequency spectrum (0.3 to 5.0 cps) appears to be in order with realistic line parameters and with the expected excitations at sea.

Maximum stress

Measurements of the dynamic stresses indicated they can be of significant magnitude occurring almost simultaneously and of equal magnitude at both ends in the relatively short laboratory test samples. Consequently, fatigue may become a serious concern for an actual sea application.

The most likely occurrence of incipient fatigue may be at or near the ship end, because at that location the state of combined stresses is the most severe. In contrast, the magnitude of the combined stresses decreases with increasing depth along a nonbuoyant line due to diminishing line weight. However, high local stress concentration can result from attaching to the cable some fittings and appendages which do not have stress-relieving design features. These conditions can cause an early failure of the cable. In such cases, failure usually occurs where these fittings are located along the submerged line.

Combined stress

A load-handling rope in the ocean can be and usually is, subjected to a combination of static and dynamic stresses which can exceed the critical stress of the rope material and cause failure. These stresses are usually axial, torsional, flexural and radial compressive and are generally identifiable. However, radial compressive stresses are not easily defined and do not lend themselves to analytical solutions. For example, in the case where two layers of individual wires are stranded in opposite lay direction, as in double-armored

cable, there is point-to-point contact between the two layers and any radial compressive stresses, such as passage over a sheave or the attachment of any bolted hardware to the line, will contribute to the high levels of localized st. ass concentration.*

The need for endurance information under combined stresses and wet conditions have become apparent. Such data would provide an ultimate meaning to field and laboratory determinations.

Elongations

During the past it was observed that at resonance the elastic elangations of the rope were toward the driven or output end. During nonresonance the elangation took place in the opposite direction, toward the input or simulated ship end. This can be observed from Fig. 19, and by noting the dynamic response Tables VI through XVI. Referring to Fig. 19, at resonant frequencies the output-input ratio is relatively high compared to the nonfrequency ratios.

For example, from Fig. 19 and Table VII, at a frequency of .60 cps the input displacement is 90 mils and the output displacement is 700 mils. The ratio is 7.78. However, at a nonresonant frequency of 1.5 cps and higher, the ratio tends to become flat but at a much lower value of .040 at 3.00 cps.

Relating these observations to a combined construction of wire and synthetic ropes, then substantially all the dynamic elongations would occur in the synthetic rope whether at resonance or at norresonance.

Problems encountered

Some experimental problem areas may be outlined as:

- 1. A comprehensive test engineering analysis was necessitated prior to the design of the experimental equipment.
- 2. The appropriateness, limitations and modifications of the existing facilities had to be thoroughly explored.
- 3. The need for a suitable, dynamic terminating fitting for the synthetic rope was required and had to be constructed so as to insure successful completion of the test program.
- * J. C. Poffenberger, E. A. Capadona, and R. B. Siter, "Dynamic testing of cables," Transactions, 2nd Annual Marine Technology Society Conference, Washington, D. C., Exploiting the ocean, pp 485–523. June 27 29, 1966.

Summary

The laboratory experiments indicated the rope material and length appeared to be the parameters which most affected the k/m expression. The tests also confirmed the relatively low natural frequencies which were expected in the considerable longer rope lengths used in the ocean.

The laboratory tests also indicated that the maximum dynamic stresses usually occur at fundamental resonant frequencies of the rope system. Measurements of these dynamic stresses showed that they can be of significant magnitude occurring simultaneously at both ends of the relatively short laboratory samples. A study of Fig. 20 and the dynamic response tables indicate this situation and also reveal that at resonance the elastic elongations of the rope are toward the driven or output end. During nonresonance, the elongation takes place in the opposite direction, toward the simulated ship end.

RECOMMENDATIONS

- 1. Closer simulation of the sea application may be obtained by introducing some of the hydraulic parameters, viz., drag, buoyancy.
- 2. Random loading of test samples should be investigated. Under random loading conditions, low frequency resonance becomes difficult to sustain because the resonant frequencies peaked very sharply and the delineation between resonant and nonvesonant state was abrupt.
- 3. Endurance data for various rope material is needed and is of great importance in the sea environment. The needed endurance data could be categorized as a high state of stress combined with a low cycle life, and a low state of stress combined with high cycle life.
- 4. Terminating fittings should be carefully selected in conjunction with the associated dynamics since the weakest link in some systems is at an near the termination.
- 5. A reliable terminating device should be designed and employed, in order to establish an adequate basis for comparison and selection of the best type of line for load-handling purposes. Then, a relatively large number of samples should be tested. Testing of several samples is desirable for any material. This desirability becomes especially acute for stranded line materials which are inherently characterized by nonuniformity of loading along the individual strands and/or among their groupings.
- 6. More sophisticated instrumentation should be developed to obtain vernier rotation measurements which could become useful, so that the amount of rotation from relatively short length laboratory samples could be extrapolated to longer field lengths. If loops had been formed and kinks developed on short lengths in the laboratory, then it could be safely assummed that loops and kinks will form on very long lengths.

7. It is recommended that the rotation kink formation phase of testing be further investigated from the standpoint of determining how much rotation is actually needed to form a loop and a kink.

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TABLE 1
TENSION ELONGATION DATA FOR WIRE ROPE SAMPLE NO. 1 *

Gage Length - 60 inches

lst Loadi	ing Cycle	Unloadir	ng Cycle	2nd Load	ling Cycle**
Load	Elongation	Load	Elongation	1,oad	Elongation
(ibs)	(ins)	(lbs)	(ins)	(lbs)	(ins)
1,000	.000	50,000	.306	10,000	.000
5,000	.047	45,000	.341	20,000	.056
10,000	.084	40,000	.298	30,000	.100
15,090	. 123	35,000	.254	40,000	.146
20,000	. 132	30,000	.228	50,000	.236
25,000	.170	25,000	. 190	55,000	.242
30,000	.202	20,000	.152	60,000	.307
35,000	.204	15,000	. 142	000رته	.329
40,000	.232	10,000	. 105		
45,000	.263	5,000	.055		
50,000	.306	1,000	.029		

^{*} See Hysteresis Curve Fig. 11.

^{**} Force multiplying pulley arrangement was installed to obtain higher loadings.

TABLE II

TENSION ELONGATION DATA FOR WIRE ROPE SAMPLE NO. 3

Gage Length - 60 inches

Load	Elongation
(lbs)	(ins)
1,000	.000
5,000	. 103
10,000	.152
15,000	. 184
20,000	.224
25,000	.260
30,000	.296
35,000	.335
40,000	.366
45,000	.410
50,000	.433
55,000	.494
60,000	.528

Wire rope failed at 66,500 pounds.

TABLE III
TENSION ELONGATION DATA FOR SYNTHETIC ROPE SAMPLE NO. 1

Gage Length - 60 inches

Load	Elongation
(lbs)	(ins)
1,000	0.00
2,009	0.50
5,000	2.00
10,000	4.31
15,000	6.50
20,000	8.44
25,600	10.63

Synthetic rope failed at 29,200 pounds.

TABLE IV

ROTATION AND ELONGATION DATA FOR WIRE ROPE

(Outdoor Measurements)

Lead	Specimen No.	Elongation	Rotation
(lbs)		(ins)	(degrees)
200		Ċ	0
4,100	2	6/64	e
7,800	4	7/64	45
11,800	6	14/64	90
15,400	8	12/64	135

(Laboratory Measurements)

l.ood	Specimen No.	Elongation	Rotation
(lbs)		(ins)	(degrees)
200		0	0
4,100	2	0 5/64	20
7,800	4	10/64	5
11,800	6	13/64	9
15,400	8	17/64	4

TABLE V

ROTATION AND ELONGATION DATA FOR SYNTHETIC ROPE

(Cutilior Measurements)

Load	Specimen No.	Elongation	Rotation
(lbs)		(ins)	(degrees)
290		0	G
2,250	1	4 11/64	G
4,500	3	7 32/64	225
6,900	7	9 43/64	45
9,000	5	³0 53/64	135

TABLE VI

Excitation Displacement: 60 Mil Peak-to-Peak

Remorts	Line Tersion: 10,250 ths	70						•														
9 10 0			8		ÿ	.25	<u>.</u> 8	×.	<u>ئ</u>	<u>ج</u>	8	<u>.</u>	8,	<u>.</u>	-	<u>8</u>	8 <u>.</u>	8	8	8	<u>8</u>	8
Fi AT		1.335	335	85.	.637	.85	8	. 38.	3 .	8	.58	38.	S S.	88.	.583	3 5.	S	S	S	3	.583	S .
Displacement Output (An)	(11m)	185	9	22	15	2	0	*	•6	\$	0	0	0	0	0	0	0	0	0	G	0	0
Bisplacement Input (61)	(III)	9	3	\$	55	\$	\$	\$	3	8	3	3	\$	જ	\$	3	\$\$	65	8	\$	\$	3
Force Output (Fo)	(lbs)	- S	280	8	8	88		98	300	250	230	82	88	8	8	8	98	86	250	8	8	906
Force Input (Fi)	Ē	Š*G		350	35	8	8	350	350	300	380	95. 95.	350	350	350	35	350	350	350	350	350	350
Frequency	(eps)	4	0.55	8	8.	01.1	9,-	<u>~</u>	3 .	*	2.	8.8	2.25	2.25	2.33	9,50	8.8	3.8	2.66	%	3.60	3.00

TABLE VI (continued)
STEEL WIRE ROPE DYNAMIC RESPONSE DATA

Excitation Displacement: 60 Mil Peak-to-Peak

Remarks		
<u>Δο</u>		88888
Fi ^i		.538 .572 .500 .572 .572
Displacement Output (∆o)	(mil)	00000
Displacement Input (△i)	(mil)	\$2222 \$2222
Force Output (Fo)	(lbs)	300 350 350 350 350 350
Force Input (Fi)	(lbs)	350 350 400 400 400
Frequency	(cps)	3.10 3.25 3.25 4.00 4.00

TABLE VII

Excitation Displacement: 120 Mil Peak-to-Peak

		T					-	_								~						 1
										Cel No.	68087	466 # /Div	` *	*	*	`						
	500 lbs	ıtion	5	1			; ;	Load Calle		Cell No.	6006W	~:U/# 89E	184 1/0;		<i>\</i>	`						
ຶ່	Line Tension: 10,600 lbs	Calibration	LVDT		20/18	8	2	l cond			µe/Div	40	2 5	2 œ	> ∀	+	Used	0.1				
Remarks	Line T			A 4.6.		0.1	0.5				Attn.	-			; -	2	Attn. Used	LVDT	Load Cells			
0 ∆ Q		3.9300	9.6000	7.7200	7.7800	6.8700	1.1300	.3590	.5830	.3200	0091	.1600	1600	. 1200	.1200	. 1200	. 1200	.1250	.0400	89/0.	0220	.0400
Σ I		1.070	3.130	3.070	3.610	3.720	1.250	8	.833	8.	.638	<u>8</u> 9.	3.	889.	.625	.625	.625	.625	.583	.615	.538	.560
Displacement Output (△o)	(mi1)	550	8	925	200	1,030	135	45	2	40	20	20	50	15	15	15	15	15	z,	<u>0</u>	2	က
Displacement Input (△i)	(lim)	071	150	145	8	140	120	125	120	125	125	125	125	125	125	125	125	120	120	130	130	125
Force Output (Fo)	(lbs)	1 500	4.400	4,050	3,900	4,700	1,300	800	906	800	700	82	82	200	009	009	909	920	009	200	009	550
Force Input (Fi)	(lbs)	2 500	700	4.450	3,250	5,200	1,500	000,1	000,1	2,000	800	750	900	008	750	750	750	750	780	800	200	700
Frequency	(cps)	44	 	0,0	0,0	99.0	0.85	00.7	00.1	7.10	1.40	1.40	1.50	1.55	1.55	1.65	1.75	1.75	2.00	2.00	2.00	2.30

TABLE VII (continued)
WIRE ROPE DYNAMIC RESPONSE DATA

Excitation Displacement: 120 Mil Peak-to-Peak

Remarks			/						n y p a de											
Δο Δi Ren		.0400	9750	. 0370	.0400	.0357	0400	0400	.0400	.0537	.0400	0000	0000	0000	0000	0000	0000	 	- 	
Fi ^i		.560	.638	.518	.638	.500	89	919.	89.	.500	.538	909.	.483	.556	.593	.536	.483			
Displacement Output (Ao)	(mil)	જ	5	2	2	2	co.	S	2	2	5	0	0	0	0	0	0			
Displacement Input (△i)	(mil)	125	125	135	125	140	125	130	125	140	130	125	145	135	135	140	145			
Force Output (Fo)	(lbs)	909	700	920	750	909	009	200	789	650	200	200	200	008	200	200	200			
Force Input (Fi)	(lbs)	200	008	78	008	200	750	800	750	700	%	750	200	750	008	750	260			
Frequency	(cps)	2.50	2.50	2.60	2.70	2.85	3.80	3.00	3.20	3.30	3.50	3.50	3.80	3.93	4.00	4.00	4.00			

TABLE VIII

Excitation Displacement: 120 Mil Peak-to-Peak

								,											 	٦
Remarks	Line Tension: 10,000 lbs	Attn. Used		-													5			
Δ <u>΄</u> ,	م در سال	.3660	.4000	1590	.1200	.0547	.0540	.0540	.0540	0510.	.0150	.0070	.0070	0000		Military (Fri		-		
ii o		.984	.913	.746	.746	.697	.697	999.	.662	2. 4	.657	.632	<u>\$</u>	.620						
Displacement Output (△o)	(mil)	\$	28	.8.	15	~	7	4	5	7	2	p	<i>~</i>	၁						
Displacement Irput (△i)	(mil)	133	125	126	125	128	127	128	135	135	136	138	139	1						
Force Output (Fc)	(sqj)	086	086	832	814	#	111	750	77.	795	3%	810	795	832						
Force Input (Fi)	(lbs)	3,100	1,128	076	940	833	8%	870	833	870	893	870	873	893						
Frequency	(sdp)	8	2.8	1.50	1.50	2.00	2.00	2.50	2.50	3.00	3.80	3.50	3.50	8.4						

TABLE IX

Excitation Displacement: 130 Mil Peck-to-Penk

Remarks	Line Tension: 10,000 lbs	Attn. Used			At .59 cps South LVDT Attn. changed														
δ <u>ι</u>		1.965	1.550	5.000	5.530	2.660	- - - - - - -	.520	.640	4.	.320	.360							
Fi		.212	.488	3.650	2.930	3.070	1.230	1.240	1.015	.884	.827	.865							
Displacement Output (△o)	(mil)	155	210	725	830	850	130	65	08	55	40	45		~				•	
Displacement Input (△i)	(mil)	133	135	145	150	150	125	125	125	125	125	125							
Force Output (Fo)	(lbs)	259	592	3,40%	3,922	4,070	1,387	1,387	011,1	980	888	943							
Force Input (Fi)	(lbs)	282	859	3,854	4,394	4,606	1,540	1,551	1,269	20,1	1,034	1,081			1000	-			
Frequency	(cias)	0.40	0.50	0.55	0.59	0.62	0.82	0.83	0.80	00.1	1.10	1.10							

TABLE X

Excitation Displacement: 130 Mil Peak-to-Peak

								,				
Remarks	Line Tension: 10,000 lbs	Used	LVDT \ Soum :	ر ا	c. Sile Control							
Δ <u>ο</u>		1.280	2.1%	5.140	5.560	6.230	2.880	2.12	.457	.417	.375	
Fi Di		.263	.830	2.690	2.950	3.470	2.330	1.350	940	098.	.860	
Displacen:ent Output (△o)	(mil)	160	785	720	805	860	360	240	55	es.	45	
Displacement Input (∆i)	(nil)	125	130	140	145	138	125	120	120	120	120	
Force Output (Fo)	(ક્વા)	277	962	3,330	3,737	4,292	2,5%	1,443	086	925	2 05	
Force Input (Fi)	(sq)	329	1,081	3,760	4,277	4,794	2,514	1,622	1,128	-,034	1,034	
Frequency	(sdo)	.425	.526	.570	009:	069.	.833	.833	90	1.050	1.080	

TABLE XI

Excitation Displacement: 120 Mil Peuk-ia-Peak

					_				 	
Remarks	Line Tension: 11,300 lbs	Attn. Used	Load Cells . 1						 	
<u>^^0</u>										
Fi ∆₹										
Displacement Output (△o)*	(inil)	0	0 0	0	0	0	0	0		
Displacement Input (△i)	(mil)	120	120	135	128	130	130	130		
Force Output (Fo)*	(sq _I)	0	00	0	0	0	0	0		
Force Input (Fi)*	(lbs)	0	00	0	0	0	0	0		
Frequency	(cps)	5.0	0. 4.	2.0	2.5	3.0	3.5	4.0		

* The force and displacement readings were below the resolution of the instrumentation. Therefore, these rendings were tabulated as zero.

TABLE XII

Excitation Displacement: 200 Mil Peak-ta-Peak

Remarks	Line Tension: 11,000 lbs	Attn. Used	3	•																	
00 10		8.	8	8.	8.	e.	8.	8	8	8	8	8	8.	8	8	8	8	8	8		
i∓ ∆		.0495	.0495	.0495	.0483	.0483	.0483	.0483	.0483	.0483	.0483	.0483	.0483	.0483	.047	.0477	.0477	.0470	.0477		
Displacement Output (Aa)	(mil)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		A
Displacement Input (Ai)	(mil)	28	8	8	195	195	195	195	195	195	195	195	195	195	197	197	197	200	197		I
Force Output (Fo)	(lbs;	8	74	Z.	74	74	74	74	74	74	74	74	74	74	74	74	74	74	74		
Force Input (Fi)	(lbs)	76	76	*6	\$5	74	86	24	8	76	94	76	76	94	8	94	76	84	8		
Frequency	(cps)	40	20	.55	09.	.63	.63	.63	.63	28.	98	66	1.00	1.50	2.00	2.50	3.60	3.50	3.70		100 mm to 100 mm

TABLE XIII

Excitation Displacement: 200 Mif Peak-to-Peak

Remarks	Line Tension: 11,000 lbs	Attn. Used	7:	-															
00 01		8.	8.	8.	8.	8.	8.	<u>8</u>	8	8	8.	8	8.	8.	8.	8.	-	-	
FI		7.78	.047	.p.	S47	.0477	27	.0477	.0477	27	.0470	.0457	.0457	.0447	.0447	.0437			
Displacement Output (△○)	(mit)	0	0	o	0	0	0	0	0	0	0	0	0	0	0	0		-	
Displacement Input (△i)	(lim)	161	197	197	197	197	197	197	197	161	200	202	205	210	210	215			
Force Output (Fn)	(sql)	74	74	74	74	7.4	74	7.	74	74	74	75	*	74	7	74			
Force Input (Fi)	(11-1)	76	*	84	76	76	2	*	76	2	75	76	76	8	2	24			
Frequency	(sdo)	04.	.45	.50	.55	%	.67	69.	.97	%.	1.50	5.00	2.50	3.00	3.50	3.80			

TABLE XIV

SYN" IETIC ROPE DYNAMIC RESPONSE DATA

Excitation Displacement: 300 Mil Peak-to-Peak

Remarks	Line Tensian: 11,000 lbs	Attn. Used	2. 100	-								-									
<u>Δ0</u>		<u></u>		.123	- %	990.	.050.	050.	.050	.050	.015	.03	010.	- 36c.	89.	8.	88.		 		_
Fi Δi		.0470	67.50	02.70	25.	0470	<u>8</u>	283	2839	.0463	:0463	848	20.	. S. S.	4.9.	<u>8</u>	.0427			·	
Displacement Output (Ao)	(mit)	65	20.00	37	20	8	15	15	15	32	S	٠n	က	7	,_	0	0				
Displacement Input (Ai)	(mil)	300	300	300	300	900	305	305	305	305	305	305	305	310	317	325	330				
Force Output (Fo)	(lbs)	=		صدر . ميمر . ميمر .	-					=	~					3)]					
Force Input (Fi)	(lhs)	[4]	7	4	143	141	.4	- 7	141	141	141	17.	7	141	7	.4.	143				
Frequency	(sds)	40	43	47	.56	09.	.62	.62	.63	.63	.94	20	05.1	2.90	2.50	3.00	3.50				

TABLE XV

Excitation Displacement: 300 Mil Peak-to-Peak

												 	 		 		 	0	
Remarks	Line Tension: 11,000 lbs	Altn. Used	2. [UV]																
\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$		8,	8	8	8	8	8	8	8	8	8								
ii 🔯		0380	8	02.00	.0270	\$ \$	25.55	25.	1610.	.0427	.0422								
Displacement Output (Ao)	(mil)	0	O	0	0	0	0	0	0	2	0								
Displacement Input (Ai)	(Film)	300	300	305	305	305	310	315	325	330	335			-		-			
Force Output (Fo)	(162)	8	8	23	%	25	8.	8	92	8	8				 		 		} - 1
Force Input (Fi)	(lbs)	117	=	<u> </u>	~	~	=	=	=	=	14:								
Fraquency	(cpx)	0;	.54	0%	8.	00.7	05.7	2.00	2.50	3.80	3.50								

TABLE XVI

Excitation Displacement: 480 MII Featsto-Peuk

Remarks	Line Tension: 11,000 lbs	bed Used	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	ر ا														
श्री श्री		.3630	.20%	82:	8	8 8 8	976	.827	.0218	.0218	.0153							
দ্ল ি		830	26.	. 2%	2	2 2 3	2	88	8870	88 75	.0488							
Displacement Output (Ao)	(IIm)	165	25	7	45	37	20	25	2	2	2							
Displacement Input (2/1)	(m.11)	455	45%	455	435	455	455	097	097	097	094		····					
Force Output (Fo)	(104)	185	\$	148	348	148	148	84.	146	148	148							
Force Input (F1)	(165)	282	235	233	235	235	235	235	235	235	235				 Different of the second			
Fraquency	(crs)	e e		0.46	0.55	0.64	0.73	0.83	0,93	0.93	20.							

TABLE XVII

WEIGHTS OF INDIVIDUAL MOVING COMPONENTS USED IN DYNAMIC RESPONSE TESTS

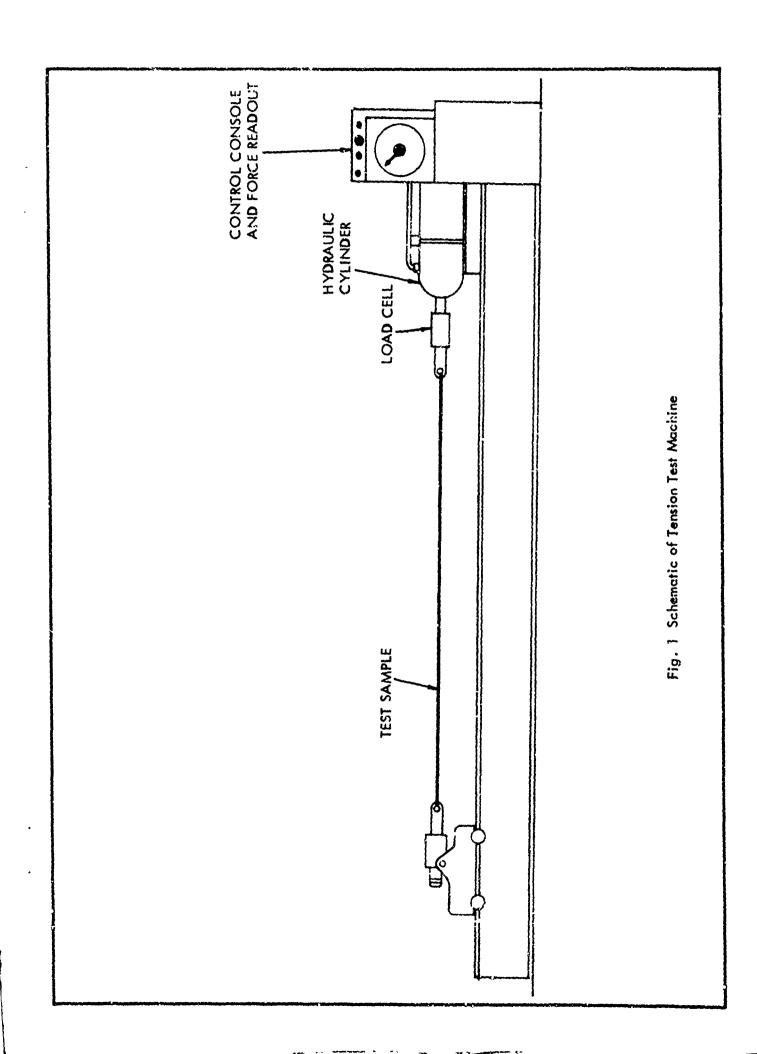
Driving End

Weight and Basket	670 lbs	6 oz
Beam and Clevis	<i>7</i> 3 lbs	7 oz
Pillow Block Shaft	11 lbs	15 oz
LVDT Actuator Core	2 !bs	0 oz
Turnbuckle Assembly	21 lbs	3 oz

Driven End

Weight and Basket	1,127 lbs	5 oz
Beam & Clevis	76 lbs	3 oz
Pillow Block Shaft	11 lbs	11 oz
LVDT Actuator Core	3 lbs	14 oz
Turnbuckle Assembly	21 lbs	12 oz
•		

Wire Rope Test Sample with Fittings	171 lbs	7 oz
Synthetic Rope Test Sample Fittings	69 lbs	8 oz



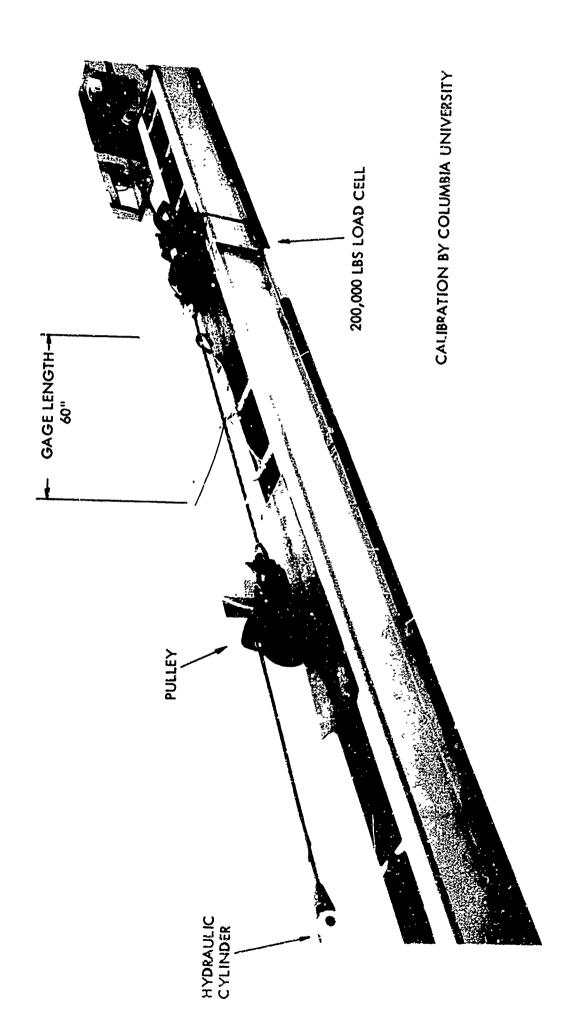


Fig. 2 Tension Test Setup for Wire Rope !Jsing Force Doubling Pulley Arrangement

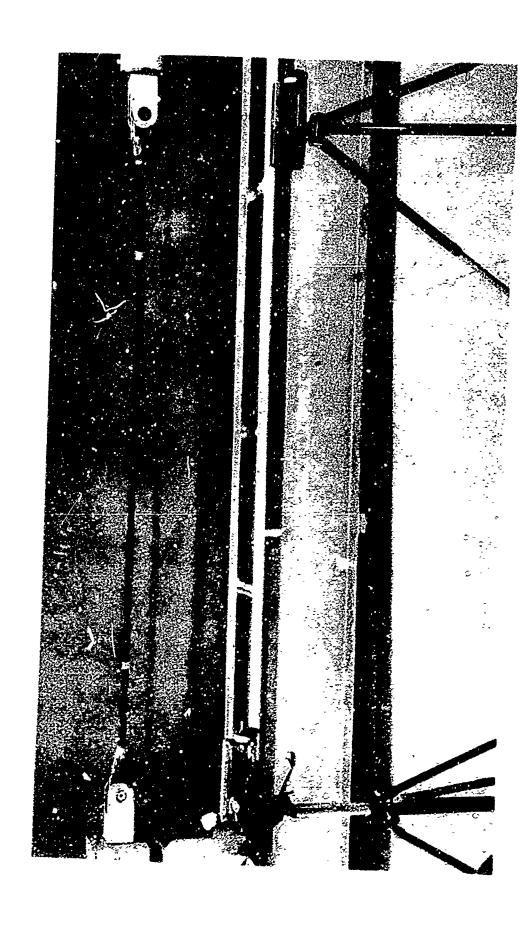


Fig. 3 Typical use of Cathometers to Measure Elongation. The Actual Test Setup is Shown in Fig. 2.

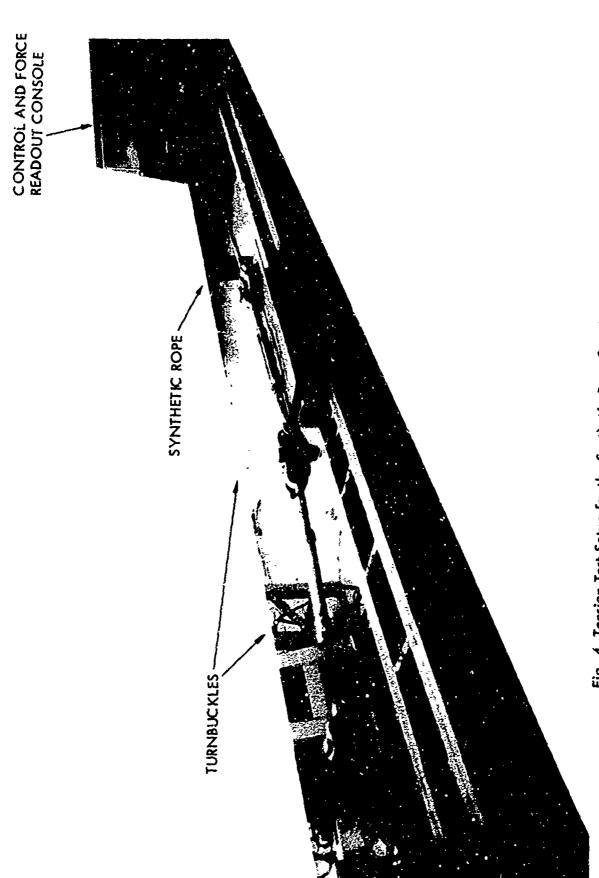


Fig. 4 Tension Test Setup for the Synthetic Rope Samples

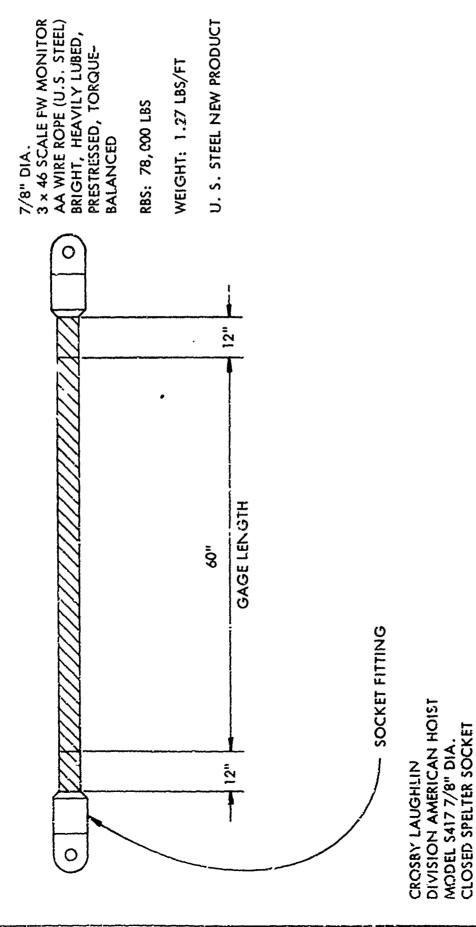
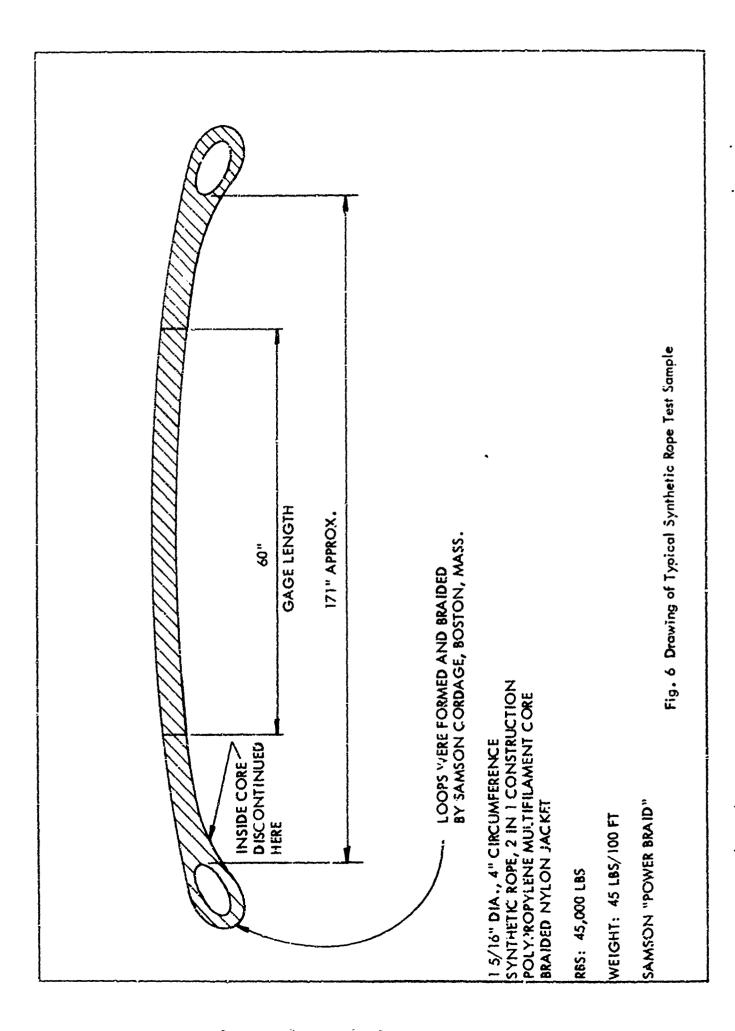
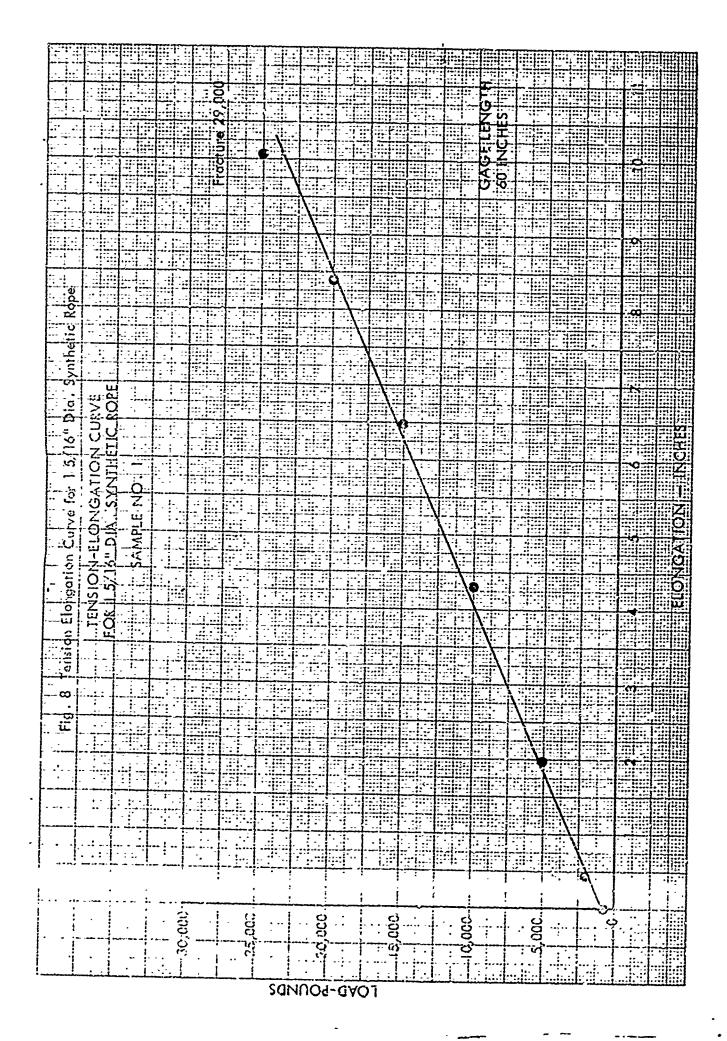


Fig. 5 Drawing of Typical Wire Rope Test Sample





rach re| 64,500 CACE TENGLE CACE TENGLE 60: INCHES ... - 4- ; ---A CURVE ± 5 Tension Elongation Curve for 7/1
TENSION ELONGATION C
FOR 7/81 DIA. WIRE RO
-5AMPLE NO. 3 Ž. Ü. -0-Ø: *-F--Ō E ONGATION 1... ans. 1 - ;-Ţ.;: • T. F 2: 000:07 0,000 30,00p LOAD-POUNDS

194 IL V 25 EN TO THE CENTIMETER 46 1513



Fig. 9 Ultimate Fracture for the Wire Rope Test Sample No. 3 Occurred at the Edge of Fitting.

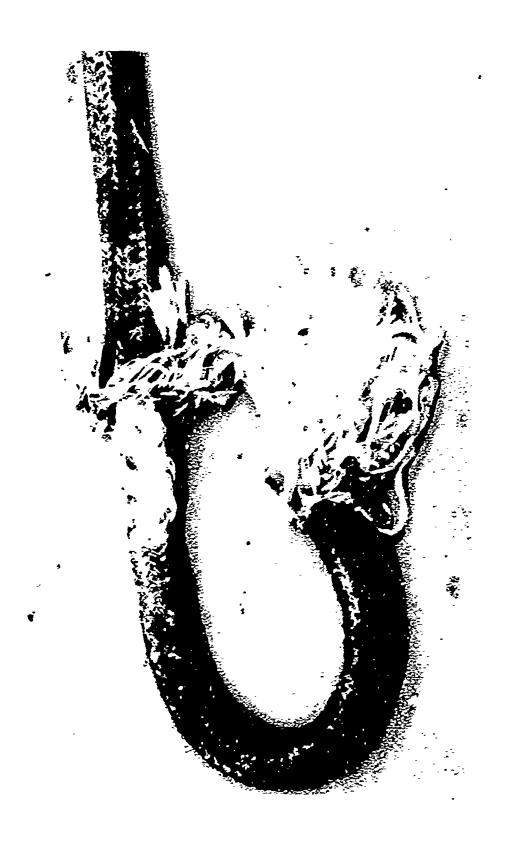
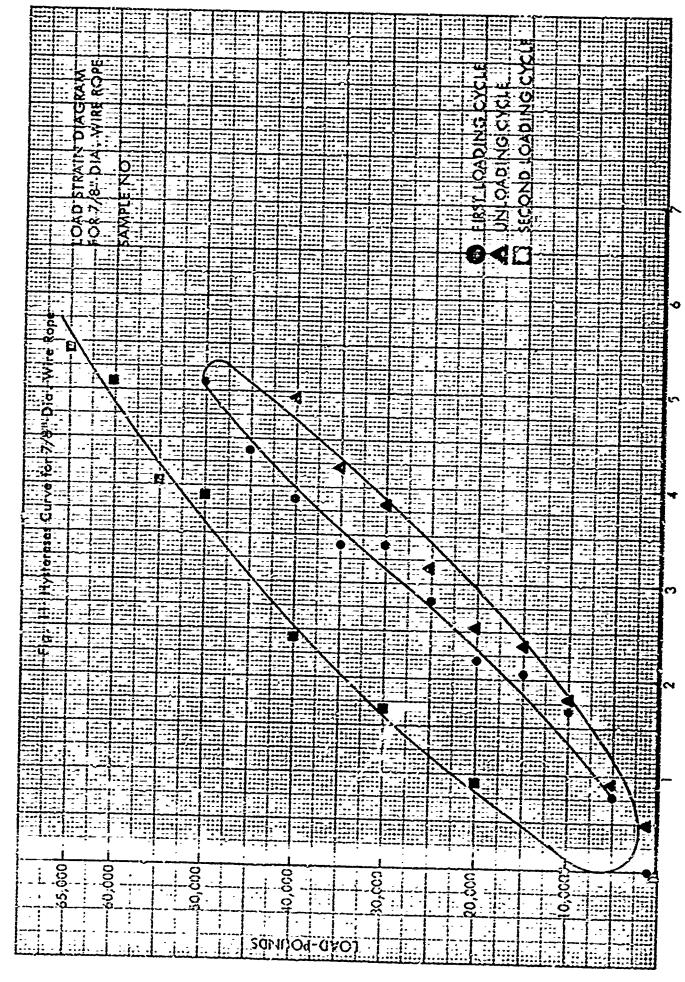
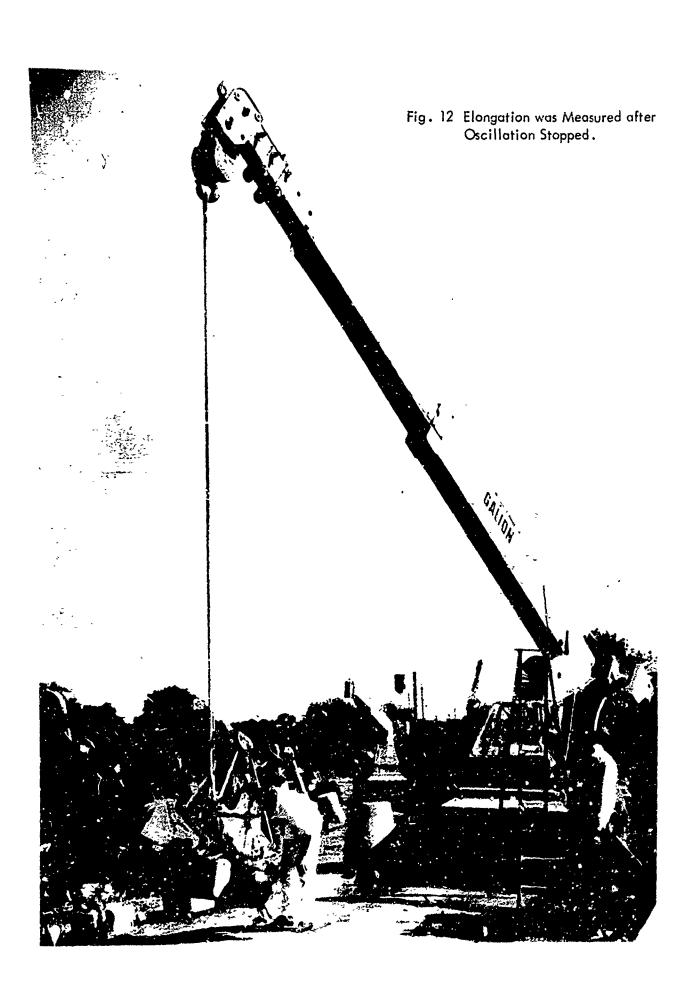


Fig. 10 Ultimate fracture of the Synthetic Rope Test Sumple No. 1 Occurred at the Junction of the Loop and the Long Length of Rope.



STRAIN INCHAINCH X 10"3



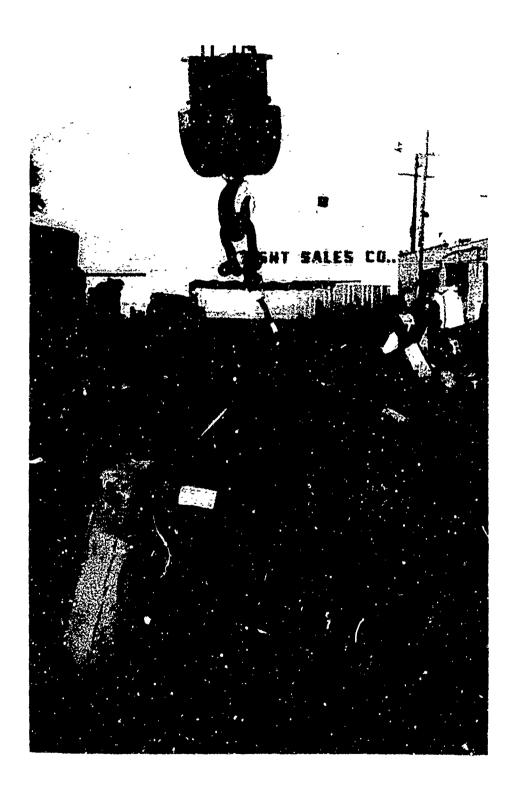


Fig. 13 Typical Result Showing the Absence of Kink Formations when the Load was Suddenly Released in the Rotation-Kink Test of the Wire Rope Samples.



Fig. 14 Typical Result Showing the Absence of Kink Formation when the Loads were Suddenly Released in the Rotation-Kink Test of the Synthetic Rope Samples.

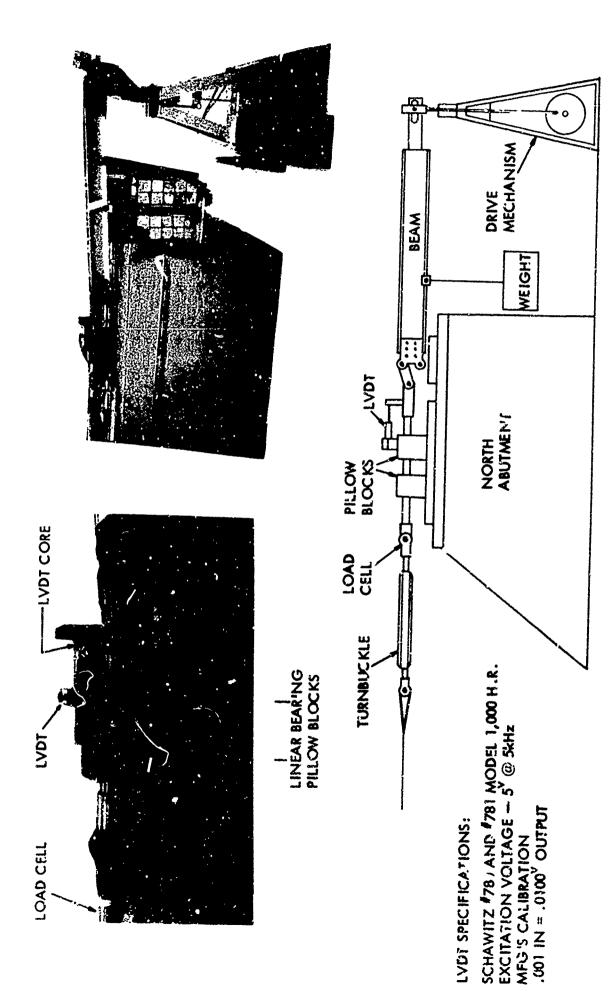


Fig. 15 Schematic of Driver End Test Setup

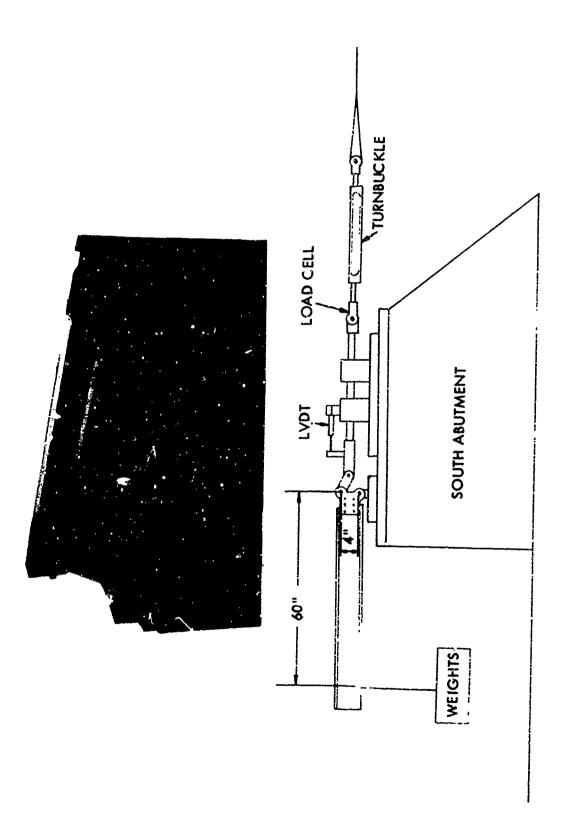
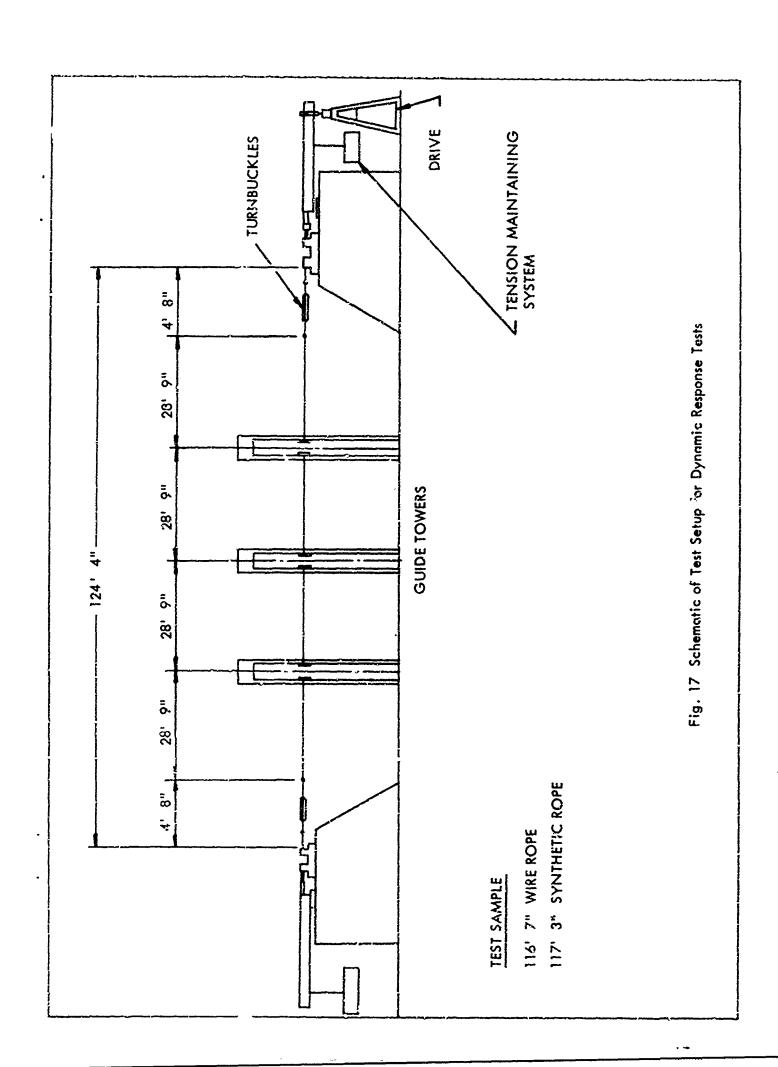
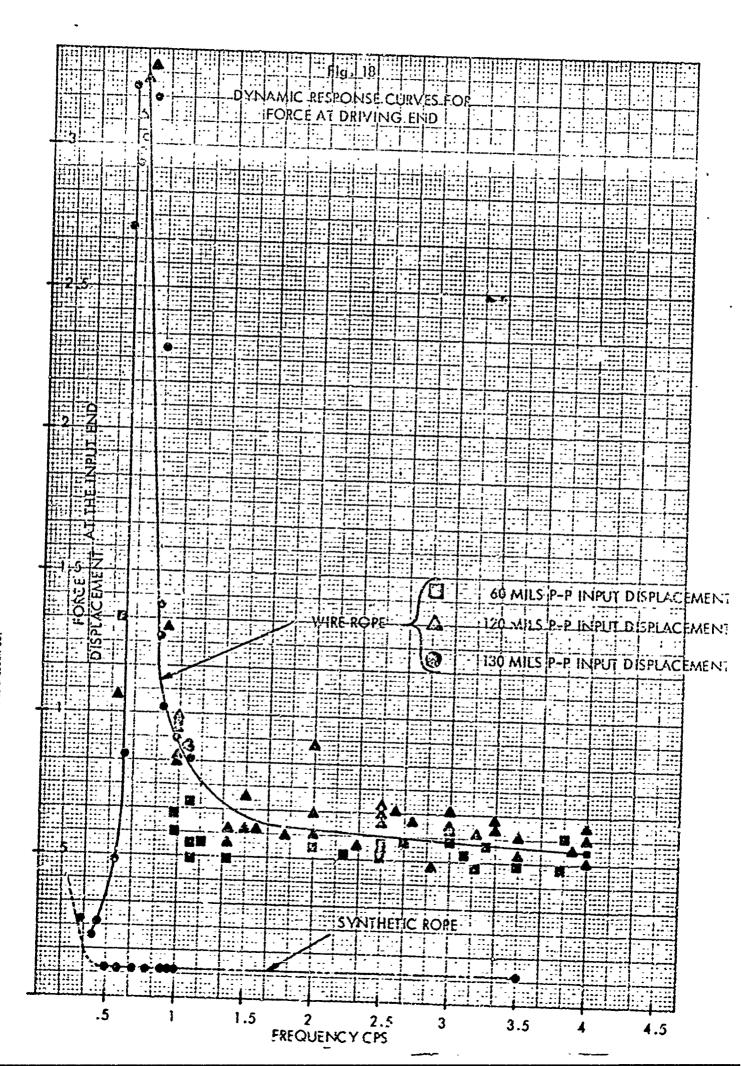
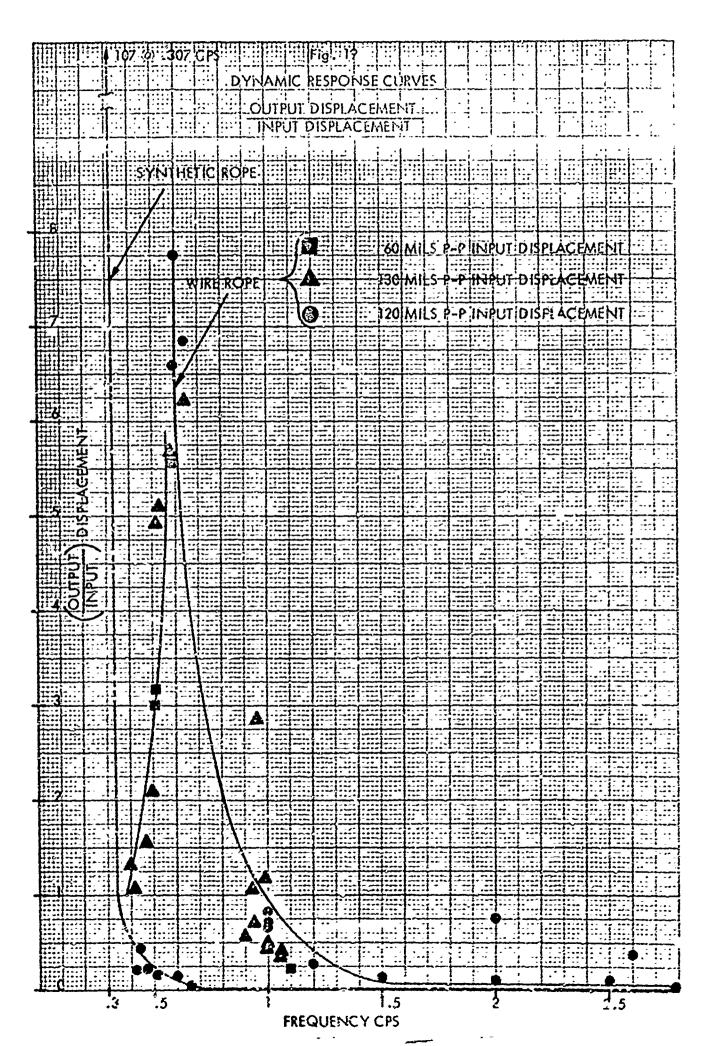


Fig. 16 Schematic of Driven End Test Setup







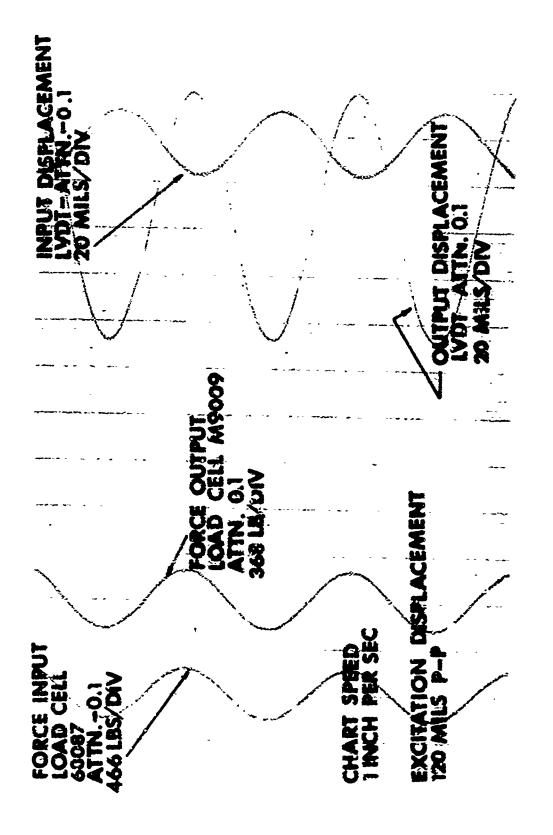


Fig. 20 Typical Oscillogram of Data for the Dynamic Response of a Wire Rope Sample

APPENDIX A

DYNAMIC EFFECTS OF LEVER ARM RATIO

Consideration !

In the ocean: a rope of undetermined length. The dampening effects of sea water were not considered.

The frequency is

$$\omega = \sqrt{\frac{K}{M}}$$
where $K = \frac{T}{\delta}$ and $\delta = \frac{TL_1}{AE}$
hence $K = \frac{AE}{L_1}$

$$\omega = \sqrt{\frac{AE}{L_1M}}$$
let $C = \sqrt{\frac{AE}{L_1M}}$

Let
$$C = \sqrt{\frac{AE}{M}}$$

$$\omega \approx C \left[\frac{1}{L_1}\right]^{\frac{1}{2}}$$

Consideration ||

In the laboratory. (Refer to Fig. 16.)

$$\omega = \frac{a}{1} \cdot \sqrt{\frac{k}{m}}$$

where
$$k = \frac{AE}{L_2}$$
; $\frac{\alpha}{T} = \frac{1}{\frac{1}{\alpha}}$; $\alpha < 1$

hence

$$\omega = \frac{1}{\sigma} \sqrt{\frac{AE}{L_2m}}$$

$$= \sqrt{\frac{AE}{\left(\frac{i}{\sigma} L_2\right)\left(\frac{1}{\sigma} m\right)}}$$

To obtain the same loading in the laboratory as expected on the ocean rope, a pivoting beam was used with a force multiplier of $\underline{1}$.

 $M = \frac{1}{a} m$

and

 $C = \sqrt{\frac{AE}{M}}$

then

$$\omega = C \left[\frac{1}{a} L_z \right]^{\frac{1}{2}}$$

It can be seen that the equivalent length of opean rope to give the same frequencies as in the laboratory test, rope is $\frac{1}{a} \times L_2$. This is equal to 15 L_2 so that 115 feet of laboratory test rope simulated an opean rope length of 1,725 feet.

A list of symbols.

a = Beam lever arm length, short length.

A = Cross sectional area of rope.

 $C = Constant \sqrt{\frac{AE}{M}}$

E = Modulus of elasticity of rope.

K = Spring constant of ocean rope.

k = Spring centrant of laboratory rape.

! = Seam lever one length, long length.

L. = Length of ocean rope.

5 = Length of laboratory rope.

 $M = Mass in ocean. = \frac{1}{6}$ (e.)

m = Mass in laboratory.

T = Rope tension.

in - Angular frequencies in radions per second.

& = Election.

Security Classification				
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Cleveland, Ohio 44103	<u></u>			
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13. SASTRACT	<u> </u>			
A testing program was initiated by U. S. N	Naval Civil Engineering	Laboratory to conduct		
dynamic tests on torque balanced wire and synthet	•	•		
Ilaboratories of Preformed Line Products Company,	•	CO-MUNICA WI TIP		
• - · · · · · · · · · · · · · · · · · ·		-4-hiishadda aalaa 4h-		
The scope of the work was to provide data		_		
basi type of line for load-handling purposes in the	•			
tension vs elongation, rotation and kink formation,	-	_		
The tension elongation tests yielded data t	ypicai to stranded line (construction.		
I				

The rotation-kink tests revealed that negligible rotations resulted in the test cables when under load and that no kinks were formed when the load was suddenly released.

The dynamic response tests showed that the measured dynamic stresses were dependent upon the exciting frequency. The natural frequency for the synthetic rope somple was 0.3 opt and 0.5 ops for the wire rope.

The tests indicated that the highest values of combined static and dynamic stresses occur at resonance which could cause failure of the cable at paints of high stress concentration.

It is recommended that some hydraulic parameters and random excitation be introduced in the future testing of this type. Stress relieving fittings should be investigated for use on load handling lines in the ocean environment.

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Unclassified

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Security Classification

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Wire Rope						
Synthetic Rope					,	
Rotation						
Torque `						
Tension Tests						
Elongation						
Longituáinal Vibration						
Strains						
Static Loads						
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